# Signature Methods in Variance Swap Pricing 

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#### Abstract

This project addresses the intricate pricing challenge of variance swaps through the application of signature methods - a novel addition to quantitative finance area in recent years. We'll construct a parameter-dense model for the ultimate calibration process, a task characterized as a high-dimensional regression.


## 1 Introduction

Variance swap is a type of financial derivative that allows investors to trade or hedge against the volatility of an underlying asset. It is a contract in which two parties agree to exchange the realized variance of the underlying asset for a predetermined fixed payment.
The underlying asset of a variance swap is typically an equity index, such as the S\&P 500, or a specific stock. The swap's payoff depends on the difference between the realized variance of the asset's returns over a specified period and a pre-agreed variance strike price. The realized variance represents the actual volatility observed in the market during the contract's duration. It is calculated based on the squared returns of the underlying asset over a specific time frame. The variance strike price $K$ is a fixed level set at the inception of the swap, representing the expected or implied volatility of the underlying asset.

Theorem 1.1. Mathematically, the payoff for a variance swap can be expressed as:

$$
\text { Payoff }=N \times\left(\sigma_{\text {realized }}^{2}-K\right)
$$

Where

- $N$ is the notional amount of the swap
- $\sigma_{\text {realized }}^{2}$ is the realized variance of the underlying asset over the life of the swap.
- $K$ is the variance strike, or the fixed variance level agreed upon at the initiation of the contract.

Theorem 1.2. The realized variance $\sigma_{\text {realized }}^{2}$ can be computed from the logarithmic returns of the underlying asset:

$$
\sigma_{\text {realized }}^{2}=\frac{1}{T} \sum_{i=1}^{T} r_{i}^{2}
$$

Where

- $r_{i}$ is the logarithmic return at time $i: r_{i}=\ln \left(\frac{S_{i}}{S_{i-1}}\right)$
- $S_{i}$ is the price of the underlying asset at time $i$.
- $T$ is the total number of observations (e.g., trading days) over the life of the swap.

Variance swaps are commonly used by investors and trades to hedge against or speculate on changes on volatility. By entering into a variance swap, market participants can effectively isolate and trade the volatility component of an asset's price movement, seperate from the asset's direction. This allows investors to manage their exposure to market volatility independently from their exposure to the asset's returns. Variance swaps provides a flexible and efficient means of gaining exposure to volatility, and they are often utilized by institutional investors, hedge funds and other sophisticated market participants. More information on variance swap we refer to [JP Morgan] Variance Swap [3].

In recent years, with the rise of big data and machine learning in finance, there have been efforts to employ neural networks and other machine learning models to predict the variance swap rates. Ferguson $\mathcal{G}$ Green (2019) [7] approximates pricing functions of derivatives using neural networks, whereas Buehler et al. (2019) focuses on optimal hedging using similar approaches. Although the learning methods have strong ability to adapt to complex patterns in data, model interpretability can be an issue. In contrast, model-based methods can capture volatility dynamics by using mathematical models such as Heston, Ornstein-Uhlenbeck process, etc., which describe the evolution of underlying assets.

With the inspiration of rough path theory work like T. Lyons (1998) 5] we find the recent development of signature method in quantitative finance. C. Cuchiero, et al.(2022) [1] formulates the time extended signature as the linear regression basis of continuous path functionals, aiming at applying data-driven, parameter-dense and tractable signature-based model in achieving outstanding calibration results in asset pricing problems.
Furthermore, C. Cuchiero, et al.(2023)[2] achieves highly accurate results in joint calibration to SPX and VIX options with signature-based models and the section 4 "Expected signature of polynomial diffusion processes" in C. Cuchiero, et al.(2023)[2] provides a direct inspiration of how signature approaches could be incorporated into describing polynomial processes and deriving close forms of expectation terms. Our work of taking signature model into computation starts from the pricing formula of variance swap and a small portion of our formula could have a similar form with VIX index presented as Theorem 5.1 in C. Cuchiero, et al.(2023) [2]. Nevertheless, our model would be much more complex that VIX index and could involve higher dimensional calibration.

Theorem 1.3. We consider asset price models whose dynamics are described by linear functions of the (time extended) signature of a primary underlying process, which is Brownian
motion in our case. Throughout the paper we fix a filtered probability space $\left(\Omega, \mathcal{F}, \mathcal{F}_{t}, \mathbb{Q}\right)$ on which we define the stochastic process

$$
d S_{t}=r S_{t} d t+\sigma_{t} S_{t} d B_{t}, \quad S_{0} \in \mathbb{R}_{+}
$$

where $S_{t}$ is the pricing process, $\sigma_{t}$ is the volatility process that will be represented by signature model. $B_{t}$ here is a Brownian motion which is correlated with $\sigma_{t}$.

The variance swap contract is structured to ensure that losses are minimized when market volatility exceeds the agreed strike price. Thus in the following theorem, we formulate the closed form for our objective strike price $K$.
Theorem 1.4. To price discretely sampled variance swaps, we first define pricing formula for vanilla variance swaps. Let the sampling dates be defined as

$$
0=t_{0}<t_{1}<\ldots<t_{N}=T
$$

where $T$ is the maturity date. The payoff of vanilla variance swap at $T$ is defined as Theorem 1.1 and Theorem 1.2. where $K$ is the strike price of the variance swap. To make the market free of arbitrage, the fair strike price $K$ under risk-free measure $\mathbb{Q}$ is given by

$$
K=\mathbb{E}^{\mathbb{Q}}\left[\left.\sum_{k=1}^{N}\left[\ln \left(\frac{S_{t_{k+1}}}{S_{t_{k}}}\right)\right]^{2} \right\rvert\, \mathcal{F}_{0}\right]
$$

From Theorem 1.3. we get

$$
S_{t_{k+1}}=S_{t_{k}} e^{r\left(t_{k+1}-t_{k}\right)-\int_{t_{k}}^{t_{k+1}} \frac{\sigma_{s}^{2}}{2} d s+\int_{t_{k}}^{t_{k+1}} \sigma_{s} d B_{s}}
$$

Then

$$
\begin{aligned}
K= & \mathbb{E}\left[\left.\sum_{k=0}^{N}\left(r\left(t_{k+1}-t_{k}\right)-\int_{t_{k}}^{t_{k+1}} \frac{\sigma_{s}^{2}}{2} d s+\int_{t_{k}}^{t_{k+1}} \sigma_{s} d B_{s}\right)^{2} \right\rvert\, \mathcal{F}_{0}\right] \\
= & \mathbb{E}\left[\sum _ { k = 0 } ^ { N } \left(r^{2}\left(t_{k+1}-t_{k}\right)^{2}-r\left(t_{k+1}-t_{k}\right) \int_{t_{k}}^{t_{k+1}} \sigma_{s}^{2} d s+2 r\left(t_{k+1}-t_{k}\right) \int_{t_{k}}^{t_{k+1}} \sigma_{s} d B_{s}\right.\right. \\
& \left.\left.+\frac{1}{4}\left(\int_{t_{k}}^{t_{k+1}} \sigma_{s}^{2} d s\right)^{2}-\int_{t_{k}}^{t_{k+1}} \sigma_{s}^{2} d s \int_{t_{k}}^{t_{k+1}} \sigma_{s} d B_{s}+\left(\int_{t_{k}}^{t_{k+1}} \sigma_{s} d B_{s}\right)^{2}\right) \mid \mathcal{F}_{0}\right] \\
= & \mathbb{E}\left[\sum _ { k = 0 } ^ { N } \left(r^{2}\left(t_{k+1}-t_{k}\right)^{2}-r\left(t_{k+1}-t_{k}\right) \int_{t_{k}}^{t_{k+1}} \sigma_{s}^{2} d s\right.\right. \\
& \left.\left.+\frac{1}{4}\left(\int_{t_{k}}^{t_{k+1}} \sigma_{s}^{2} d s\right)^{2}-\int_{t_{k}}^{t_{k+1}} \sigma_{s}^{2} d s \int_{t_{k}}^{t_{k+1}} \sigma_{s} d B_{s}+\int_{t_{k}}^{t_{k+1}} \sigma_{s}^{2} d s\right) \mid \mathcal{F}_{0}\right] \\
& \quad \sum_{k=0}^{N}\left(r^{2}\left(t_{k+1}-t_{k}\right)^{2}+\left(1-r\left(t_{k+1}-t_{k}\right)\right) \int_{t_{k}}^{t_{k+1}} \sigma_{s}^{2} d s+\frac{1}{4}\left(\int_{t_{k}}^{t_{k+1}} \sigma_{s}^{2} d s\right)^{2}\right. \\
& \left.\left.-\int_{t_{k}}^{t_{k+1}} \sigma_{s}^{2} d s \int_{t_{k}}^{t_{k+1}} \sigma_{s} d B_{s}\right) \mid \mathcal{F}_{0}\right]
\end{aligned}
$$

## 2 Signature Model

In the section we'll be introducing the signature based model. The signature is an object associated with a path which captures many of the path's important analytic and geometric properties. The detailed theoretical properties and some numerical applications are discussed in Chevyrev 8 Kormilitzin (2016) [8].

### 2.1 Notions

- (Tensor Algebra) For $n, d \in \mathbb{N}$, the $n$-fold tensor product of $\mathbb{R}^{d}$ is given by

$$
\left(\mathbb{R}^{d}\right)^{\otimes n}=\underbrace{\left(\mathbb{R}^{d}\right) \otimes\left(\mathbb{R}^{d}\right) \otimes \ldots \otimes\left(\mathbb{R}^{d}\right)}_{\mathrm{n}}
$$

where we construct an nd -dimensional space out of $n$ vectors from $\mathbf{d}$-dimensional space.
For $d \in \mathbb{N}$, the extended tensor algebra on $\mathbb{R}^{d}$ is given by

$$
T\left(\mathbb{R}^{d}\right)=\left\{\mathbf{a}=\left(a_{0}, a_{1}, \ldots, a_{n}\right): a_{i} \in\left(\mathbb{R}^{d}\right)^{\otimes i}, i=0,1,2, \ldots, n\right\}
$$

which could provide a structural understanding of term signature, which should be represented as a collection of iterated integrals of a path.

- (Operations) Suppose $\mathbf{a}=\left(a_{i}\right)_{i=0}^{\infty}, \mathbf{b}=\left(b_{i}\right)_{i=0}^{\infty} \in T\left(\left(\mathbb{R}^{d}\right)\right)$, define the sum + and product $\otimes$ by

$$
\begin{gathered}
\mathbf{a}+\mathbf{b}:=\left(a_{i}+b_{i}\right)_{i=0}^{\infty}, \\
\mathbf{a} \otimes \mathbf{b}:=\left(\sum_{k=0}^{i} a_{k} \otimes b_{i-k}\right)_{i=0}^{\infty}
\end{gathered}
$$

- (Multi-index) Suppose a multi-index $I:=\left(i_{1}, i_{2}, \ldots, i_{n}\right)$, then we set $|I|:=n$. Remark that we also set $I^{\prime}:=\left(i_{1}, \ldots, i_{n-1}\right)$ and $I^{\prime \prime}:=\left(i_{1}, \ldots, i_{n-2}\right)$ whenever needed. We also have the notation $\{I:|I|=n\}:=\{1,2, \ldots, d\}^{n}$.
Now we combine the multi-index with the tensor basis:

$$
e_{I}=e_{i_{1}} \otimes e_{i_{2}} \otimes \ldots e_{i_{n}}
$$

where $e_{i_{1}}, e_{i_{2}}, \ldots, e_{i_{n}}$ denotes the canonical basis vectors of $\mathbb{R}^{d}$. Denoting that $e_{\emptyset}$ is the basis element corresponding to $\left(\mathbb{R}^{d}\right)^{\otimes 0}$.

- Suppose we have $e_{I}:|I|=N$ to be an orthonormal basis of $\left(\mathbb{R}^{d}\right)^{\otimes N}$. Then for any $\mathbf{a} \in T\left(\left(\mathbb{R}^{d}\right)\right)$, it can be written as

$$
\mathbf{a}=\sum_{|I|>=0} a_{I} e_{I}
$$

where $a_{I} \in \mathbb{R}$ is a coefficient for a vector basis on multi-index $I$. Equivalently,

$$
a_{I}=\left\langle e_{I}, \mathbf{a}\right\rangle
$$

### 2.2 Definitions

Theorem 2.1 (Definition 2.1 [1]). Let $\left(X_{t}\right)_{t \in[0, T]}$ be a continuous $\mathbb{R}^{d}$-valued semimartingale. The signature of $X$ is the $T\left(\left(\mathbb{R}^{d}\right)\right)$-valued process $(s, t) \mapsto \mathbb{X}_{s, t}$ whose components are recursively defined as

$$
\begin{gathered}
\left\langle e_{\emptyset}, \mathbb{X}_{s, t}\right\rangle=1 \\
\left\langle e_{I}, \mathbb{X}_{s, t}\right\rangle=\int_{s}^{t}\left\langle e_{I^{\prime}}, \mathbb{X}_{s, t}\right\rangle \circ d X_{r}^{i_{n}}
\end{gathered}
$$

for each $I=\left(i_{1}, i_{2}, \ldots, i_{n}\right), I^{\prime}=\left(i_{1}, i_{2}, \ldots, I_{n-1}\right)$ and $0 \leqslant s \leqslant t \leqslant T$, where $\circ$ denotes the Stratonovich integral. Its projection $\mathbb{X}^{N}$ on $T^{(N)}\left(\mathbb{R}^{d}\right)$ is given by

$$
\mathbb{X}_{s, t}^{N}=\sum_{|I| \leqslant N}\left\langle e_{I}, \mathbb{X}_{s, t}\right\rangle e_{I}
$$

and is called signature of $X$ truncated at level $N$.
The equivalent notation:
$\mathbb{X}_{t}=\left(1, \int_{0}^{t} 1 \circ d X_{s}^{1}, \ldots, \int_{0}^{t} 1 \circ d X_{s}^{d}, \int_{0}^{t}\left(\int_{0}^{t} 1 \circ d X_{s}^{1}\right) \circ d X_{s}^{1}, \ldots, \int_{0}^{t}\left(\int_{0}^{t} 1 \circ d X_{s}^{d}\right) \circ d X_{s}^{d}, \ldots\right)$
Signature is a collection of iterated integrals of the given multidimensional path. The integrals are listed in the collection in a strict order. Similar to 1.2 .1 presented in Chevyrev 83 Kormilitzin (2016)[8], here is an example for a single signature term.
Example.

$$
\left\langle e_{1}, \mathbb{X}_{s, t}\right\rangle=\int_{0}^{t} 1 \circ d X_{s}^{1}=X_{t}^{1}-X_{s}^{1}
$$

Note that $\left\langle e_{1} \otimes e_{2}, \mathbb{X}_{s, t}\right\rangle \neq\left\langle e_{2} \otimes e_{1}, \mathbb{X}_{s, t}\right\rangle$ as $\left\langle e_{1} \otimes e_{2}, \mathbb{X}_{s, t}\right\rangle=\int_{0}^{t}\left(\int_{0}^{t} 1 \circ d X_{s}^{1}\right) \circ d X_{s}^{2}$ while $\left\langle e_{2} \otimes e_{1}, \mathbb{X}_{s, t}\right\rangle=\int_{0}^{t}\left(\int_{0}^{t} 1 \circ d X_{s}^{2}\right) \circ d X_{s}^{1}$
Theorem 2.2 (Definition 2.2 [1]). (Shuffle Product) Given two multi-indices $I=\left(i_{1}, i_{2}, \ldots, i_{n}\right)$ and $J=\left(j_{1}, j_{2}, \ldots, j_{m}\right)$, the shuffle product is defined recursively as

$$
e_{I} Ш e_{J}=\left(e_{I^{\prime}} Ш e_{J}\right) \otimes e_{i_{n}}+\left(e_{I} \amalg e_{J^{\prime}}\right) \otimes e_{j_{m}}
$$

where $e_{I} Ш e_{\emptyset}=e_{\emptyset} \amalg e_{I}=e_{I}$.
Proposition 2.1. Shuffle Property[Proposition 2.3 [1]] Let $\left(\left(X_{t}\right)\right) t \in[0, T]$ be a continuous $\mathbb{R}^{d}$-valued semimartingale and $I, J$ be two multi-indices. Then

$$
\left\langle e_{I}, \mathbb{X}_{s, t}\right\rangle\left\langle e_{J}, \mathbb{X}_{s, t}\right\rangle=\left\langle e_{I} Ш e_{J}, \mathbb{X}_{s, t}\right\rangle
$$

Proof. We prove this proposition by induction with Stratonovich integrals.
Induction Basis. $\left\langle e_{\emptyset}, \mathbb{X}_{s, t}\right\rangle\left\langle e_{J}, \mathbb{X}_{s, t}\right\rangle=1\left\langle e_{J}, \mathbb{X}\right\rangle=\left\langle e_{\emptyset} \amalg e_{J}, \mathbb{X}_{s, t}\right\rangle$, which agrees with the propostion.
Induction Steps. Assumed that for arbitrary subsets $S_{1}$ and $S_{2}$ of multi indices I and J, we have

$$
\left\langle e_{S_{1}}, \mathbb{X}_{s, t}\right\rangle\left\langle e_{S_{2}}, \mathbb{X}_{s, t}\right\rangle=\left\langle e_{S_{1}} ш e_{S_{2}}, \mathbb{X}_{s, t}\right\rangle
$$

After that,

$$
\begin{aligned}
\left\langle e_{I}, \mathbb{X}_{s, t}\right\rangle\left\langle e_{J}, \mathbb{X}_{s, t}\right\rangle & =\int_{s}^{t}\left\langle e_{J}, \mathbb{X}_{s, u}\right\rangle \circ d\left\langle e_{I}, \mathbb{X}_{s, u}\right\rangle+\int_{s}^{t}\left\langle e_{I}, \mathbb{X}_{s, u}\right\rangle \circ d\left\langle e_{J}, \mathbb{X}_{s, u}\right\rangle \\
& =\int_{s}^{t}\left\langle e_{I^{\prime}}, \mathbb{X}_{s, r}\right\rangle\left\langle e_{J}, \mathbb{X}_{s, r}\right\rangle \circ d \mathbb{X}_{r}^{i_{n}}+\int_{s}^{t}\left\langle e_{I}, \mathbb{X}_{s, r}\right\rangle\left\langle e_{J^{\prime}}, \mathbb{X}_{s, r}\right\rangle \circ d \mathbb{X}_{r}^{j_{m}} \\
& =\int_{s}^{t}\left\langle e_{I^{\prime}} Ш e_{J}, \mathbb{X}_{s, r}\right\rangle \circ d \mathbb{X}_{r}^{i_{n}}+\int_{s}^{t}\left\langle e_{I} Ш e_{J^{\prime}}, \mathbb{X}_{s, r}\right\rangle \circ d \mathbb{X}_{r}^{j_{m}} \\
& =\left\langle e_{I^{\prime}} Ш e_{J} \otimes e_{i_{n}}, \mathbb{X}_{s, t}\right\rangle+\left\langle e_{I} Ш e_{J^{\prime}} \otimes e_{j_{m}}, \mathbb{X}_{s, t}\right\rangle \\
& =\left\langle e_{I^{\prime}} Ш e_{J} \otimes e_{i_{n}}+e_{I} Ш e_{J^{\prime}} \otimes e_{j_{m}}, \mathbb{X}_{s, t}\right\rangle \\
& =\left\langle e_{I} \amalg e_{J}, \mathbb{X}_{s, t}\right\rangle
\end{aligned}
$$

Proposition 2.2 (Chen's identity). [Lemma 2.10[1]] Let $\left(X_{t}\right)_{t \in[0, T]}$ be an $\mathbb{R}^{d}$-valued semimartingale. Then

$$
\mathbb{X}_{s, t}=\mathbb{X}_{s, u} \otimes \mathbb{X}_{u, t}
$$

for each $s \leqslant u \leqslant t \leqslant T$. This can equivalently be written as

$$
\left\langle e_{I}, \mathbb{X}_{s, t}\right\rangle=\sum_{e_{I_{1}} \otimes e_{I_{2}}=e_{I}}\left\langle e_{I_{1}}, \mathbb{X}_{s, u}\right\rangle\left\langle e_{I_{2}}, \mathbb{X}_{u, t}\right\rangle
$$

where I represents an arbitrary multi-index.
Proof. We prove this by induction on the length of the multi-index $I$.
Induction Basis. When $|I|=0$, obviously the statement holds.
Induction Steps. Assumed that the statement holds for all multi-indices $J \subseteq I$, where $|J|<n$ and $I=\left(i_{1}, i_{2}, \ldots, i_{n}\right)$. Then,

$$
\begin{aligned}
\left\langle e_{I}, \mathbb{X}_{s, t}\right\rangle & =\int_{s}^{t}\left\langle e_{I^{\prime}}, \mathbb{X}_{s, r}\right\rangle \circ d \mathbb{X}_{r}^{i_{n}} \\
& =\int_{s}^{u}\left\langle e_{I^{\prime}}, \mathbb{X}_{s, r}\right\rangle \circ d \mathbb{X}_{r}^{i_{n}}+\int_{u}^{t}\left\langle e_{I^{\prime}}, \mathbb{X}_{s, r}\right\rangle \circ d \mathbb{X}_{r}^{i_{n}} \\
& =\left\langle e_{I}, \mathbb{X}_{s, u}\right\rangle+\int_{u}^{t} \sum_{e_{I_{1}} \otimes e_{I_{2}^{\prime}}=e_{I^{\prime}}}\left\langle e_{I_{1}^{\prime}}, \mathbb{X}_{s, u}\right\rangle\left\langle e_{I_{2}^{\prime}}, \mathbb{X}_{u, r}\right\rangle \circ d \mathbb{X}_{r}^{i_{n}} \\
& =\left\langle e_{I}, \mathbb{X}_{s, u}\right\rangle+\sum_{e_{I_{1}^{\prime}} \otimes e_{I_{2}^{\prime}}=e_{I^{\prime}}}\left\langle e_{I_{1}^{\prime}}, \mathbb{X}_{s, u}\right\rangle\left\langle e_{I_{2}^{\prime}} \otimes e_{i_{n}}, \mathbb{X}_{u, t}\right\rangle \\
& =\sum_{e_{I_{1}} \otimes e_{I_{2}}=e_{I}}\left\langle e_{I_{1}}, \mathbb{X}_{s, u}\right\rangle\left\langle e_{I_{2}}, \mathbb{X}_{u, t}\right\rangle
\end{aligned}
$$

Note: paying attention to the difference between shuffle $\amalg$ and tensor product $\otimes$.
Theorem 2.3. Our goal is to parameterize the volatility process $\sigma_{t}$ as a signature model (Sig-SDE), which is, applying signature model to describe the dynamics of $S_{t}$ as

$$
\sigma_{t}(\ell)=\ell_{\emptyset}+\sum_{|I| \leq n} \ell_{I}\left\langle e_{I}, \widehat{\mathbb{W}}_{t}\right\rangle
$$

where $W$ is the underlying d-dimensional Brownian motion and $\widehat{W}_{t}=\left(t, W_{t}\right)$.
Remark. With the same motivation,

$$
\left(\sigma_{t}(\ell)\right)^{2}=\ell_{\emptyset}+\sum_{|I|,|J| \leq n} \ell_{I} \ell_{J}\left\langle e_{I} Ш e_{J}, \widehat{\mathbb{W}}_{t}\right\rangle
$$

## 3 Expected Signature

Theorem 3.1. Since every polynomial function in the signature has a linear representation, suppose the d-dimensional real-valued process $X$ is a weak solution of

$$
d X_{t}=b\left(\widehat{\mathbb{X}}_{t}\right) d t+\sqrt{a\left(\widehat{\mathbb{X}}_{t}\right)} d W_{t}
$$

where $W$ is a d-dimensional Brownian motion and $a$ and $b$ are linear maps. Thus we can define $X$ as a polynomial process:

$$
d X_{t}=b\left(X_{t}\right) d t+\sqrt{a\left(X_{t}\right)} d W_{t}, \quad X_{0}=x_{0}
$$

where maps a $: \mathbb{R}^{d} \mapsto \mathbb{S}_{+}^{d}$ and $b: \mathbb{R}^{d} \mapsto \mathbb{R}^{d}$ such that each $a_{i j}$ is a polynomial of degree at most 2 and $b_{j}$ is a polynomial of degree at most 1 for each $i, j=1, \ldots, d+1$. Furthermore, to define the correlation between processes $X$ and $B$, we introduce process $Z=\left(X_{t}, B_{t}\right)$ and denote its time extension by $\widehat{Z}=(t, X, B)$ with its signature $\left(\widehat{\mathbb{Z}}_{t}\right)_{t \geq 0}$. Thus, the correlation matrix process between $X$ and $B$ can be defined as

$$
\rho_{i j}=\frac{\left[Z^{i}, Z^{j}\right]}{\sqrt{\left[Z^{i}\right]} \sqrt{\left[Z^{j}\right]}} \in[-1,1]
$$

for all $i, j=1, \ldots, d+1$, where $[$,$] denotes the quadratic variation. In this case, the volatility$ process $\sigma_{t}$ can be defined equivalently as a signature model (Sig-SDE) of the primary process $Z$ :

$$
\sigma_{t}(\ell)=\ell_{\emptyset}+\sum_{|I| \leq n, e_{i} \neq d+1} \ell_{I}\left\langle e_{I}, \widehat{\mathbb{Z}}_{t}\right\rangle
$$

Theorem 3.2. [Lemma 4.1 in [2] ] Let $\left(X_{t}\right)_{t \geq 0}$ be the polynomial process given by (4) and $b, a$ be the corresponding drift and diffusion coefficients. Then

$$
\begin{gathered}
b_{j}(x)=b_{j}^{c}+\sum_{k=1}^{d} b_{j}^{k} x_{k} \\
a_{i j}(x)=a_{i j}^{c}+\sum_{k=1}^{d} a_{i j}^{k} x_{k}+\sum_{k, h=1}^{d} a_{i j}^{k h} x_{k} x_{h}
\end{gathered}
$$

for $b_{j}^{c}, b_{j}^{k}, a_{i j}^{c}, a_{i j}^{k}, a_{i j}^{k h} \in \mathbb{R}$
Moreover we have,

$$
b_{j}\left(Y_{t}\right)=\left\langle\boldsymbol{b}_{j}, \mathbb{Y}_{t}^{1}\right\rangle
$$

and

$$
a_{i j}\left(Y_{t}\right)=\left\langle\boldsymbol{a}_{i j}, \mathbb{Y}_{t}^{2}\right\rangle
$$

where

$$
\begin{gathered}
\boldsymbol{b}_{j}=b_{j}^{c} e_{\emptyset}+\sum_{k=1}^{d}\left(b_{j}^{k} X_{0}^{k} e_{\emptyset}+b_{j}^{k} e_{k}\right)=\left(b_{j}^{c}+\sum_{k=1}^{d} b_{j}^{k} X_{0}^{k}\right) e_{\emptyset}+\sum_{k=1}^{d} b_{j}^{k} e_{k} \\
\boldsymbol{a}_{i j}=\left(a_{i j}^{c}+\sum_{k=1}^{d} a_{i j}^{k} X_{0}^{k}+\sum_{k, h=1}^{d} a_{i j}^{k h} X_{0}^{k} X_{0}^{h}\right) e_{\emptyset}+\sum_{k=1}^{d}\left(a_{i j}^{k}+2 \sum_{h=1}^{d} a_{i j}^{k h} X_{0}^{h}\right) e_{k}+\sum_{k, h=1}^{d} a_{i j}^{k h} e_{k} Ш e_{h}
\end{gathered}
$$

Theorem 3.3 (Lemma 4.2 [2].). Let $\left(X_{t}\right)_{t \geq 0}$ be the polynomial process given by (4) and take $b, a$ from Theorem 3.2. The truncated signature $\left(\mathbb{X}_{t}^{n}\right)_{t \geq 0}$ is a polynomial process and for each $|I| \leq n$ it holds that

$$
\left\langle e_{I}, \mathbb{X}_{t}^{n}\right\rangle=\int_{0}^{t}\left\langle L e_{I}, \mathbb{X}_{s}^{n}\right\rangle d s+\int_{0}^{t}\left\langle e_{I^{\prime}}, \mathbb{X}_{s}^{n}\right\rangle \sigma_{i_{|I|}}\left(X_{s}\right) d W_{s}
$$

where the operator $L: T\left(\mathbb{R}^{d}\right) \rightarrow T\left(\mathbb{R}^{d}\right)$ satisfies $L\left(T^{(n)}\left(\mathbb{R}^{d}\right)\right) \subseteq T^{(n)}\left(\mathbb{R}^{d}\right)$ and is given by

$$
L e_{I}=e_{I^{\prime}} \uplus \boldsymbol{b}_{i_{|I|}}+\frac{1}{2} e_{I^{\prime \prime}} \amalg \boldsymbol{a}_{i_{|I|-1} i_{|I|}}
$$

Definition 3.1. [Definition 4.3 in [2].] For each $|I| \leq n$ set then $\eta_{I J} \in \mathbb{R}$ such that

$$
L e_{I}=\sum_{|J| \leq n} \eta_{I J} e_{J}
$$

Then we fix a labelling injective function $\mathcal{L}:\{I:|I| \leq n\} \rightarrow\left\{1,2, \ldots, d_{n}\right\}$. We then call the matrix $G \in \mathbb{R}^{d_{n} \times d_{n}}$ where

$$
G_{\mathcal{L}(I) \mathcal{L}(J)}=\eta_{I J}
$$

the $d_{n}$ dimensional matrix representative of $L$.
Theorem 3.4 (Theorem 4.4 in [2].). Let $\left(X_{t}\right)_{t \geq 0}$ be the polynomial process given by (4). $\left((F)_{t}\right)_{t \geq 0}$ be the filtration generated by $\left(Y_{t}\right)_{t \geq 0}$ and let $G$ be the $d_{n}$-dimensional matrix representative of the dual operator corresponding to $\mathbb{X}$. Then for each $T, t \geq 0,|I| \leq n$ we have

$$
\mathbb{E}\left[\left\langle e_{I}, \mathbb{X}_{T+t}\right\rangle \mid \mathcal{F}_{T}\right]=\sum_{|J| \leq n}\left(e^{t G^{\top}}\right)_{\mathcal{L}(I) \mathcal{L}(J)}\left\langle e_{J}, \mathbb{X}_{T}\right\rangle
$$

Here we introduce a lifting operator $\mathbf{P}$ which is defined as:

$$
\mathbf{P}_{t}^{I}\left(\mathbb{X}_{T}\right)=\mathbb{E}\left[\left\langle e_{I}, \mathbb{X}_{T+t}\right\rangle \mid \mathcal{F}_{T}\right]=\sum_{|J| \leq n}\left(e^{t G^{\boldsymbol{\top}}}\right)_{\mathcal{L}(I) \mathcal{L}(J)}\left\langle e_{J}, \mathbb{X}_{T}\right\rangle
$$

Remark. Here's an another case when $0 \leq t_{0}<t_{1}<t_{2}$, by Tower's property and Theorem 3.4

$$
\begin{aligned}
\mathbb{E}\left[\left\langle e_{I}, \mathbb{X}_{t_{2}}\right\rangle\left\langle e_{H}, \mathbb{X}_{t_{1}}\right\rangle \mid \mathcal{F}_{t_{0}}\right] & =\mathbb{E}\left[\mathbb{E}\left[\left\langle e_{I}, \mathbb{X}_{t_{2}}\right\rangle \mid \mathcal{F}_{t_{1}}\right]\left\langle e_{H}, \mathbb{X}_{t_{1}}\right\rangle \mid \mathcal{F}_{t_{0}}\right] \\
& =\mathbb{E}\left[\sum_{|J| \leq n}\left(e^{\left(t_{2}-t_{1}\right) G^{\boldsymbol{\top}}}\right)_{\mathcal{L}(I) \mathcal{L}(J)}\left\langle e_{J}, \mathbb{X}_{t_{1}}\right\rangle\left\langle e_{H}, \mathbb{X}_{t_{1}}\right\rangle \mid \mathcal{F}_{t_{0}}\right] \\
& =\mathbb{E}\left[\sum_{|J| \leq n}\left(e^{\left(t_{2}-t_{1}\right) G^{\top}}\right)_{\mathcal{L}(I) \mathcal{L}(J)}\left\langle e_{J} Ш e_{H}, \mathbb{X}_{t_{1}}\right\rangle \mid \mathcal{F}_{t_{0}}\right] \\
& =\sum_{|J| \leq n}\left(e^{\left(t_{2}-t_{1}\right) G^{\boldsymbol{\top}}}\right)_{\mathcal{L}(I) \mathcal{L}(J)} \mathbb{E}\left[\left\langle e_{J} Ш e_{H}, \mathbb{X}_{t_{1}}\right\rangle \mid \mathcal{F}_{t_{0}}\right] \\
& =\sum_{|J| \leq n}\left(e^{\left(t_{2}-t_{1}\right) G^{\boldsymbol{\top}}}\right)_{\mathcal{L}(I) \mathcal{L}(J)} \mathbf{P}_{t_{1}-t_{0}}^{J \amalg H}\left(\mathbb{X}_{t_{0}}\right) \\
& =\Phi^{\left(I, t_{2}\right),\left(H, t_{1}\right)}\left(\mathbb{X}_{t_{0}}\right)
\end{aligned}
$$

## 4 Calibration of variance swap price with signature model

Theorem 4.1. Assume Theorem 1.4 and the linear signature presentation for dynamic process, the risk-neutral strike $K$ for variance swap is given by

$$
K=\sum_{k=0}^{N}\left(r^{2}\left(t_{k+1}-t_{k}\right)^{2}+\left(1-r\left(t_{k+1}-t_{k}\right)\right) \mathcal{K}_{t_{k}, t_{k+1}}^{1}+\frac{1}{4} \mathcal{K}_{t_{k}, t_{k+1}}^{2}-\mathcal{K}_{t_{k}, t_{k+1}}^{3}\right)
$$

where

$$
\begin{aligned}
& \text { - (1) } \mathcal{K}_{t_{k}, t_{k+1}}^{1}=\sum_{|I|,|J| \leq n} \ell_{I} \ell_{J}\left(\mathbf{P}_{t_{k+1}}^{I \amalg J \otimes \mathbf{0}}\left(\widehat{\mathbb{W}}_{0}\right)-\mathbf{P}_{t_{k}}^{I \amalg J \otimes \mathbf{0}}\left(\widehat{\mathbb{W}}_{0}\right)\right) \\
& \text { - (2) } \mathcal{K}_{t_{k}, t_{k+1}}^{2}=\sum_{|I|,|J|,|M|,|N| \leq n} \ell_{I} \ell_{J} \ell_{M} \ell_{N}\left(\mathbf{P}_{t_{k+1}}^{(I \amalg J \otimes \mathbf{0}) \uplus(M ш N \otimes \mathbf{0})}\left(\widehat{\mathbb{W}}_{0}\right)+\mathbf{P}_{t_{k}}^{(I \amalg J \otimes \mathbf{0}) \uplus(M ш N \otimes \mathbf{0})}\left(\widehat{\mathbb{W}}_{0}\right)\right. \\
& \left.-2 \Phi^{\left(I Ш J \otimes \mathbf{0}, t_{k+1}\right),\left(M ш N \otimes \mathbf{0}, t_{k}\right)}\left(\widehat{\mathbb{W}}_{0}\right)\right) \\
& \text { - (3) } \mathcal{K}_{t_{k}, t_{k+1}}^{3}=\sum_{|I|,|J|,|M| \leq n} \ell_{I} \ell_{J} \ell_{M}\left(\mathbf{P}_{t_{k+1}}^{(I \amalg J \otimes \mathbf{0}) ш \tilde{M}^{d+1}}\left(\widehat{\mathbb{Z}}_{0}\right)+\mathbf{P}_{t_{k}}^{(I \amalg J \otimes \mathbf{0}) ш \tilde{M}^{d+1}}\left(\widehat{\mathbb{Z}}_{0}\right)\right. \\
& \left.-\Phi^{\left(I \amalg J \otimes \mathbf{0}, t_{k+1}\right),\left(\tilde{M}^{d+1}, t_{k}\right)}\left(\widehat{\mathbb{Z}}_{0}\right)-\Phi^{\left(\tilde{M}^{d+1}, t_{k+1}\right),\left(I \amalg J \otimes 0, t_{k}\right)}\left(\widehat{\mathbb{Z}}_{0}\right)\right)
\end{aligned}
$$

Proof. See appendix $A$.

## 5 Model Modification

In section 4 , our general process is given by $\widehat{Z}_{t}=\left(t, W_{t}, B_{t}\right)$ where $t$ is the time process, $W$ is the underlying d-dimensinal brownian motion and $B$ is the one dimensional brownian motion from the pricing formula.

According Theorem [3.1, we introduced the general diffusion process $X_{t}$ into our study. Note that the process $X_{t}$ is also driven by underlying d-dimensinal brownian motion $W_{t}$. That provides an inspiration to us to apply high-level process into calibration instead of calibrating directly on the underlying brownian motions.

The only thing that needs to be modified here is the $G$ matrix. Our future work would be incorporating OU process and Heston model into our project.

## A Appendix A

The full proof for Theorem 4.1.

- step 1. We take $\mathcal{K}_{t_{k}, t_{k+1}}^{1}=\mathbb{E}\left[\int_{t_{k}}^{t_{k+1}} \sigma_{s}^{2} d s\right]$. With Remark 2.2 where we apply signature formula in term $\sigma$ and Theorem 3.4

$$
\begin{aligned}
& \mathcal{K}_{t_{k}, t_{k+1}}^{1}=\mathbb{E}\left[\int_{t_{k}}^{t_{k+1}} \sigma_{s}^{2} d s\right] \\
& =\mathbb{E}\left[\int_{t_{k}}^{t_{k+1}} \sum_{|I|,|J| \leq n} \ell_{I} \ell_{J}\left\langle e_{I} Ш e_{J}, \widehat{\mathbb{W}}_{s}\right\rangle d s\right] \\
& =\mathbb{E}\left[\int_{0}^{t_{k+1}} \sum_{|I|,|J| \leq n} \ell_{I} \ell_{J}\left\langle e_{I} Ш e_{J}, \widehat{\mathbb{W}}_{s}\right\rangle d s\right]-\mathbb{E}\left[\int_{0}^{t_{k}} \sum_{|I|,|J| \leq n} \ell_{I} \ell_{J}\left\langle e_{I} Ш e_{J}, \widehat{\mathbb{W}}_{s}\right\rangle d s\right] \\
& =\mathbb{E}\left[\sum_{|I|,|J| \leq n} \ell_{I} \ell_{J}\left\langle e_{I} Ш e_{J} \otimes e_{0}, \widehat{\mathbb{W}}_{t_{k+1}}\right\rangle\right]-\mathbb{E}\left[\sum_{|I|,|J| \leq n} \ell_{I} \ell_{J}\left\langle e_{I} \amalg e_{J} \otimes e_{0}, \widehat{\mathbb{W}}_{t_{k}}\right\rangle\right] \\
& =\sum_{|I|,|J| \leq n} \ell_{I} \ell_{J} \mathbb{E}\left[\left\langle e_{I} Ш e_{J} \otimes e_{0}, \widehat{\mathbb{W}}_{t_{k+1}}\right\rangle\right]-\sum_{|I|,|J| \leq n} \ell_{I} \ell_{J} \mathbb{E}\left[\left\langle e_{I} Ш e_{J} \otimes e_{0}, \widehat{\mathbb{W}}_{t_{k}}\right\rangle\right] \\
& =\sum_{|I|,|J| \leq n} \ell_{I} \ell_{J} \mathbf{P}_{t_{k+1}}^{I \amalg J \otimes \mathbf{0}}\left(\widehat{\mathbb{W}}_{0}\right)-\sum_{|I|,|J| \leq n} \ell_{I} \ell_{J} \mathbf{P}_{t_{k}}^{I \amalg J \otimes \mathbf{0}}\left(\widehat{\mathbb{W}}_{0}\right) \\
& =\sum_{|I|,|J| \leq n} \ell_{I} \ell_{J}\left(\mathbf{P}_{t_{k+1}}^{I \amalg J \otimes \mathbf{0}}\left(\widehat{\mathbb{W}}_{0}\right)-\mathbf{P}_{t_{k}}^{I \amalg J \otimes \mathbf{0}}\left(\widehat{\mathbb{W}}_{0}\right)\right)
\end{aligned}
$$

- step 2. $\mathcal{K}_{t_{k}, t_{k+1}}^{2}=\mathbb{E}\left[\left(\int_{t_{k}}^{t_{k+1}} \sigma_{s}^{2} d s\right)^{2}\right]$. With Theorem 3.4 and Remark 3

$$
\begin{aligned}
\mathcal{K}_{t_{k}, t_{k+1}}^{2} & =\mathbb{E}\left[\left(\int_{t_{k}}^{t_{k+1}} \sigma_{s}^{2} d s\right)^{2}\right] \\
& =\mathbb{E}\left[\left(\int_{0}^{t_{k+1}} \sigma_{s}^{2} d s-\int_{0}^{t_{k}} \sigma_{s}^{2} d s\right)^{2} \mid \mathcal{F}_{0}\right] \\
& =\mathbb{E}\left[\left(\int_{0}^{t_{k+1}} \sigma_{s}^{2} d s\right)^{2}+\left(\int_{0}^{t_{k}} \sigma_{s}^{2} d s\right)^{2}-2\left(\int_{0}^{t_{k+1}} \sigma_{s}^{2} d s \int_{0}^{t_{k}} \sigma_{s}^{2} d s\right) \mid \mathcal{F}_{0}\right] \\
& =\sum_{|I|,|J|,|M|,|N| \leq n} \ell_{I} \ell_{J} \ell_{M} \ell_{N}\left(\mathbf{P}_{t_{k+1}}^{(I \amalg J \otimes \mathbf{0}) \amalg(M ш N \otimes \mathbf{0})}\left(\widehat{\mathbb{W}}_{0}\right)+\mathbf{P}_{t_{k}}^{(I \amalg J \otimes \mathbf{0}) \uplus(M ш N \otimes \mathbf{0})}\left(\widehat{\mathbb{W}}_{0}\right)\right. \\
& \left.-2 \Phi^{\left(I \amalg J \otimes \mathbf{0}, t_{k+1}\right),\left(M ш N \otimes \mathbf{0}, t_{k}\right)}\left(\widehat{\mathbb{W}}_{0}\right)\right)
\end{aligned}
$$

- step 3. Before we dive into the actual computation of the cross term, we introduce the special case when we take the extra correlated Brownian process $B$ into the picture. If we take $W$ as our multidimensional brownian process and the underlying primary process under the signature model of $\sigma=\sum_{|I| \leq n} \ell_{I}\left\langle e_{I}, \widehat{\mathbb{W}}\right\rangle$, here we need to define
the process $Z=(W, B)$ and the time-extended version $\widehat{Z}=(t, W, B)$ as well as its signature $\widehat{\mathbb{Z}}$.

Assumption A.1. C. Cuchiero, G. Gazzani, S. Svaluto-Ferro(2022) [1] For all $i \in$ $1,2, \ldots, d$, we have

$$
d\left[W^{i}, Z^{d+1}\right]_{t}=\sum_{|J| \leq m} a_{i(d+1)}^{J}\left\langle e_{J}, \widehat{\mathbb{Z}}_{t}\right\rangle d t
$$

for some $m \in \mathbb{N}$ where $\widehat{Z}=(t, W, B)$.
Now we compute the special case correlated with B.

$$
\begin{align*}
\int_{0}^{T} \sigma_{s} d Z_{s}^{d+1} & =\int_{0}^{T} \sigma_{s} \circ d Z_{s}^{d+1}-\frac{1}{2}\left[\sigma, Z^{d+1}\right]_{T} \\
& =\int_{0}^{T} \sum_{|I| \leq n} \ell_{I}\left\langle e_{I}, \widehat{\mathbb{Z}}_{s}\right\rangle \circ d Z_{s}^{d+1}-\frac{1}{2}\left[\sum_{|I| \leq n} \ell_{I}\left\langle e_{I}, \widehat{\mathbb{Z}}\right\rangle, Z^{d+1}\right]_{T} \\
& =\sum_{|I| \leq n} \ell_{I}\left\langle e_{I} \otimes e_{d+1}, \widehat{\mathbb{Z}}_{T}\right\rangle-\frac{1}{2} \int_{0}^{T} \sum_{|I| \leq n} \ell_{I}\left\langle e_{I^{\prime}}, \widehat{\mathbb{Z}}_{s}\right\rangle d\left[Z^{i_{|I|}}, Z^{d+1}\right]_{s} \\
& =\sum_{|I| \leq n} \ell_{I}\left(\left\langle e_{I} \otimes e_{d+1}, \widehat{\mathbb{Z}}_{T}\right\rangle-\frac{1}{2} \int_{0}^{T}\left\langle e_{I^{\prime}}, \widehat{\mathbb{Z}}_{s}\right\rangle d\left[Z^{i_{|I|}}, Z^{d+1}\right]_{s}\right)  \tag{1}\\
& =\sum_{|I| \leq n} \ell_{I}\left(\left\langle e_{I} \otimes e_{d+1}, \widehat{\mathbb{Z}}_{T}\right\rangle-\frac{1}{2} \sum_{|J| \leq m} a_{i_{|I|}(d+1)}^{J}\left\langle e_{I^{\prime}} Ш e_{J} \otimes e_{0}, \widehat{\mathbb{Z}}_{T}\right\rangle\right)  \tag{2}\\
& =\sum_{|I| \leq n} \ell_{I}\left(\left\langle e_{I} \otimes e_{d+1}-\frac{1}{2} \sum_{|J| \leq m} a_{i_{|I|} d+1}^{J} e_{I^{\prime}} Ш e_{J} \otimes e_{0}, \widehat{\mathbb{Z}}_{T}\right\rangle\right) \\
& =\sum_{|I| \leq n} \ell_{I}\left\langle\tilde{e}_{I}^{d+1}, \widehat{\mathbb{Z}}_{T}\right\rangle
\end{align*}
$$

where $\tilde{e}_{I}^{d+1}=e_{I} \otimes e_{d+1}-\frac{1}{2} \sum_{|J| \leq m} a_{i_{|I|} d+1}^{J} e_{I^{\prime}} Ш e_{J} \otimes e_{0}$.
(Note that the highest order of $\tilde{e}_{I}^{d+1}$ is $n+m$ )
From (1) to (2) with assumption A.1:

$$
\begin{aligned}
\int_{0}^{T}\left\langle e_{I^{\prime}}, \widehat{\mathbb{Z}}_{s}\right\rangle d\left[Z^{i_{|I|}}, Z^{d+1}\right]_{s} & =\int_{0}^{T}\left\langle e_{I^{\prime}}, \widehat{\mathbb{Z}}_{s}\right\rangle \sum_{|J| \leq m} a_{i_{\mid I} d+1}^{J}\left\langle e_{J}, \widehat{\mathbb{Z}}_{s}\right\rangle d s \\
& =\int_{0}^{T} \sum_{|J| \leq m} a_{i_{|I|}}^{J} d+1
\end{aligned}\left\langle e_{I^{\prime}}, \widehat{\mathbb{Z}}_{s}\right\rangle\left\langle e_{J}, \widehat{\mathbb{Z}}_{s}\right\rangle d s
$$

Remark. When we are not incorporate any process form (like OU, Heston) into our model and we are calibrating directly on the underlying brownian motions, the term could be written as

$$
\tilde{e}_{I}^{d+1}=e_{I} \otimes e_{d+1}-\frac{1}{2} \sigma^{i_{|I|}} \rho_{i_{|I|} d+1} e_{I^{\prime}} \otimes e_{0}
$$

Now we compute the explicit formula of the cross term.

$$
\begin{aligned}
& \mathbb{E}\left[\int_{t_{k}}^{t_{k+1}} \sigma_{s}^{2} d s \int_{t_{k}}^{t_{k+1}} \sigma_{s} d Z_{s}^{d+1}\right] \\
&= \mathbb{E}\left[\int_{t_{k}}^{t_{k+1}} \sigma_{s}^{2} d s \int_{t_{k}}^{t_{k+1}} \sigma_{s} d Z_{s}^{d+1} \mid \mathcal{F}_{0}\right] \\
&= \mathbb{E}\left[\left(\int_{0}^{t_{k+1}} \sigma_{s}^{2} d s-\int_{0}^{t_{k}} \sigma_{s}^{2} d s\right)\left(\int_{0}^{t_{k+1}} \sigma_{s} d Z^{d+1} s-\int_{0}^{t_{k}} \sigma_{s} d Z^{d+1} s\right) \mid \mathcal{F}_{0}\right] \\
&= \mathbb{E}\left[\int_{0}^{t_{k+1}} \sigma_{s}^{2} d s \int_{0}^{t_{k+1}} \sigma_{s} d Z^{d+1} s+\int_{0}^{t_{k}} \sigma_{s}^{2} d s \int_{0}^{t_{k}} \sigma_{s} d Z^{d+1} s\right. \\
&\left.-\int_{0}^{t_{k+1}} \sigma_{s}^{2} d s \int_{0}^{t_{k}} \sigma_{s} d Z^{d+1} s-\int_{0}^{t_{k+1}} \sigma_{s} d Z^{d+1} s \int_{0}^{t_{k}} \sigma_{s}^{2} d s \mid \mathcal{F}_{0}\right] \\
&= \sum_{|I|,|J,|M| \leq n} \ell_{I} \ell_{J} \ell_{M}\left(\mathbf{P}_{t_{k+1}}^{(I \amalg J \otimes \mathbf{0}) ш \tilde{M}^{d+1}}\left(\widehat{\mathbb{Z}}_{0}\right)+\mathbf{P}_{t_{k}}^{(I \amalg J \otimes \mathbf{0}) ш \tilde{M}^{d+1}}\left(\widehat{\mathbb{Z}}_{0}\right)\right. \\
&-\left.\Phi^{\left(I \amalg J \otimes \mathbf{0}, t_{k+1}\right),\left(\tilde{M}^{d+1}, t_{k}\right)}\left(\widehat{\mathbb{Z}}_{0}\right)-\Phi^{\left(\tilde{M}^{d+1}, t_{k+1}\right),\left(I \amalg J \otimes \mathbf{0}, t_{k}\right)}\left(\widehat{\mathbb{Z}}_{0}\right)\right)
\end{aligned}
$$

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