

Branching Diffusions Representation for Nonlinear PDEs

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Outline

- 1 Introduction : From Galton-Watson trees to KPP equation
- 2 Generalized KPP equation
 - Polynomial nonlinearity in v
 - Polynomial nonlinearity in (v, Dv)
- 3 Initial Value Problems
 - Linear IVP
 - Semilinear IVP

From linear representation (ii) to nonlinear

- Consider **KPP equations**

$$(KPP) \quad \partial_t v + \frac{1}{2} \Delta v + \beta \left(\sum_{i=1}^n p_i v^i - v \right) = 0$$

with $p_i > 0$ and $\sum_{k=1}^n p_i = 1$

- **Branching diffusions** representation :

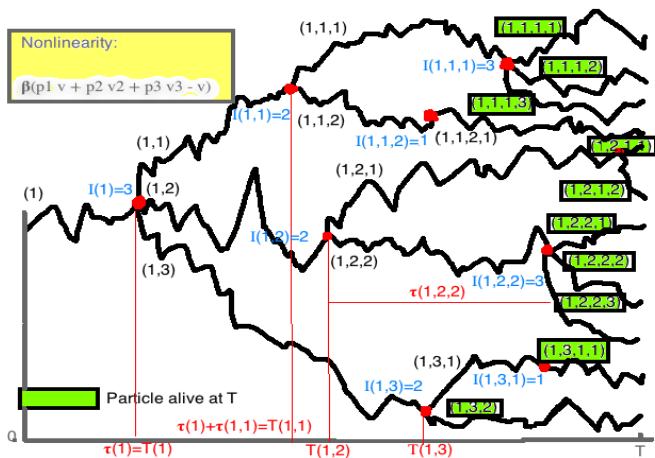
$$v(0, x) = \mathbb{E} \left[\prod_{k \in \mathcal{K}_T} g(Z_T^k) \right], \quad \text{where } Z^k : k\text{-th particle}$$

and

$$\mathcal{K}_t := \{ \text{All particles alive at time } t \}$$

[Skorokhod, Watanabe, McKean]

Branching diffusion ($n = 3$)



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Generalized KPP equation

Let $a_i(t, x)$ be bounded functions, and consider the PDE

$$\partial_t v + \mu(t, x) \cdot Dv + \frac{1}{2} \sigma^2(t, x) : D^2 v + \sum_{i=0}^n p_i a_i(t, x) v^i = 0$$

$$v(T, \cdot) = g$$

Introduce the branching diffusion :

- $(\tau_k)_k$ iid $\sim \rho$, and $T_k := T \wedge (\tau_1 + \dots + \tau_k)$: branching times
- $(I_k)_k$ iid Multinomial(p_0, \dots, p_n) : number of decedents
- Particle k dies out at the branching event T_k , and I_k **independent** particles defined by

$$dX_t = \mu(t, X_t) dt + \sigma(t, X_t) dW_t, \quad W \text{ Brownian motion}$$



The branching diffusion representation

Recall $\mathcal{K}_T := \{\text{particles present at } T\}$

$\bar{\mathcal{K}}_T := \cup_{t \leq T} \mathcal{K}_t$: all particles

Theorem (Henry-Labordère, Tan & NT SPA '14)

Let $\rho > 0$ density on $(0, \infty)$, and $\bar{\rho}(t) := \int_t^\infty \rho(s) ds$. Then

$$v(0, x) = \mathbb{E}_{0, x} \left[\prod_{k \in \mathcal{K}_T} \frac{g(Z_T^k)}{\bar{\rho}(\Delta T)} \prod_{k \in \bar{\mathcal{K}}_T \setminus \mathcal{K}_T} \frac{a_{l_k}(T_k, Z_{T_k}^k)}{\rho(\Delta T_k)} \right]$$

Moreover, this representation extends to the path-dependent case

- Numerical implications
- In the rest of the talk : extension to more general nonlinearities

Sketch of proof ($\mu \equiv 0$, $\sigma \equiv 1$, so $X = \text{BM}$)

Feynman-Kac's formula \equiv Duhamel's representation (with Heat kernel as fundamental solution of Heat equation)

$$v(0, x) = \mathbb{E}_{0, x} \left[g(X_T) + \int_0^T \sum_{i=1}^n p_i a_i(t, X_t) v(t, X_t)^i \right]$$

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Continue with the nonlinear term to **get rid of the regression** :

$$\begin{aligned} v(\tau_1, X_{\tau_1})^{h_1} &= \mathbb{E}_{\tau_1, X_{\tau_1}} [\phi(\tau_2, X_{\tau_2}, l_2)]^{h_1} \\ &= \underbrace{\mathbb{E}_{\tau_1, X_{\tau_1}} [\phi(\tau_2, X_{\tau_2}, l_2)] \times \dots \times \mathbb{E}_{\tau_1, X_{\tau_1}} [\phi(\tau_2, X_{\tau_2}, l_2)]}_{h_1 \text{ times}} \\ &= \mathbb{E}_{\tau_1, X_{\tau_1}} [\phi(\tau_{1,1}, Z_{\tau_{1,1}}^{1,1}, h_{1,1}) \times \dots \times \phi(\tau_{1,l}, Z_{\tau_{1,l}}, h_{1,l})] \end{aligned}$$

.... Tower property... Number of branching $\rightarrow \infty$

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A class of semilinear PDEs with polynomial nonlinearity

Consider the PDE (unit diffusion for simplicity)

$$\partial_t u + \frac{1}{2} \Delta u + f(t, x, u, Du) = 0, \quad u_T = g$$

with nonlinearity (e.g. Burger's equation in 1d uDu)

$$f(t, x, y, z) = \sum_{(\ell_i)_{0 \leq i \leq n} \in L} p_\ell c_\ell(t, x) y^{\ell_0} \prod_{i=1}^n (b_i(t, x) \cdot z)^{\ell_i}$$

- L finite subset of \mathbb{N}^{n+1}
- $p_\ell > 0$ with $\sum_{\ell \in L} p_\ell = 1$
- $b_i(t, x)$ bounded functions

Illustration in the context of the Burger's equation

By the Feynman-Kac formula

$$\begin{aligned} v(0, x) &= \mathbb{E}_{0,x} \left[\frac{\bar{\rho}(T)}{\bar{\rho}(T)} g(X_T) + \int_0^T (vDv)(t, X_t) \frac{\rho(t)}{\rho(t)} dt \right] \\ &= \mathbb{E}_{0,x} \left[\mathbb{I}_{\tau_1 > T} \frac{g(X_T)}{\bar{\rho}(T)} + \mathbb{I}_{\tau_1 \leq T} \frac{(vDv)(\tau_1, X_{\tau_1})}{\rho(\tau_1)} \right] =: \mathbb{E}_{0,x} [\phi(\tau_1, X_{\tau_1})] \end{aligned}$$

Continue with the nonlinear term to **get rid of the regression** :

$$\begin{aligned} (vDv)(\tau_1, X_{\tau_1}) &= \mathbb{E}_{\tau_1, X_{\tau_1}} [\phi(\tau_2, X_{\tau_2})] \partial_x \mathbb{E}_{\tau_1, X_{\tau_1}} [\phi(\tau_2, X_{\tau_2})] \\ &= \mathbb{E}_{\tau_1, X_{\tau_1}} [\phi(\tau_2, X_{\tau_2})] \mathbb{E}_{\tau_1, X_{\tau_1}} \left[\frac{W_{\tau_2} - W_{\tau_1}}{\tau_2 - \tau_1} \phi(\tau_2, X_{\tau_2}) \right] \\ &= \mathbb{E}_{\tau_1, X_{\tau_1}} \left[\phi(\tau_{1,1}, Z_{\tau_{1,1}}^{1,1}) \frac{W_{\tau_2} - W_{\tau_1}}{\tau_2 - \tau_1} \phi(\tau_{1,2}, Z_{\tau_{1,2}}) \right] \end{aligned}$$

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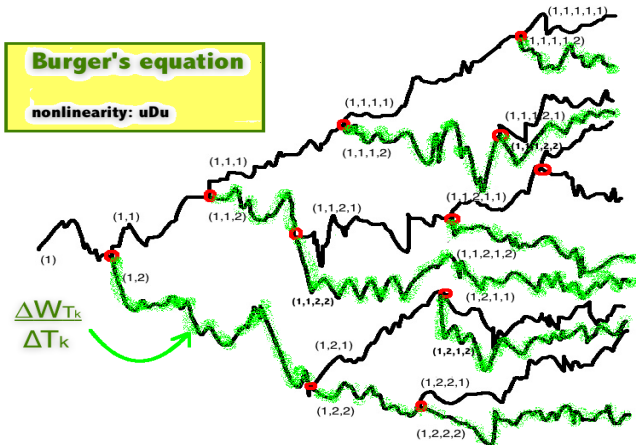
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.... **Tower property**... **Number of branching** $\longrightarrow \infty \dots$

Branching diffusion for the Burger equation

Example : Burgers equation $d = 1$ and $f(t, x, u, u_x) = u u_x$



Likelihood ratio (Malliavin) automatic differentiation

For simplicity, $d = 1$, constant μ , $\sigma = 1$: $X_h = x + \mu h + W_h$

$$\partial_x \mathbb{E}[\phi(X_h)] = \mathbb{E} \left[\phi(X_h) \frac{W_h}{h} \right]$$

Direct integration by parts

$$\begin{aligned} \partial_x \mathbb{E}[\phi(X_h)] &= \mathbb{E}[\phi_x(X_h)] = \int \phi_x(x+y) \frac{e^{-\frac{1}{2h}(y-\mu h)^2}}{\sqrt{2\pi h}} dy \\ &= \int \phi(x+y) \frac{(y-\mu h)}{h} \frac{e^{-\frac{1}{2h}(y-\mu h)^2}}{\sqrt{2\pi h}} dy \\ &= \mathbb{E} \left[\phi(X_h) \frac{W_h}{h} \right] \end{aligned}$$

Marked branching mechanism

- $(\tau_k)_k$ iid arrival times, $T_k := \tau_k \wedge T$
- $(I_k)_k$ iid Multinomial($\ell, p_\ell, \ell \in L$)
- If $T_1 < T$: particle dies out at T_1
 - $I_1 = \ell = (\ell_0, \dots, \ell_n)$ with probability p_ℓ
 - birth of new particles :
 ℓ_i particles of type $i, i = 0, \dots, n$
- $\mathcal{K}_t = \{k \text{ alive at time } t\}, \bar{\mathcal{K}}_t := \cup_{s \leq t} \mathcal{K}_s$, for all $k \in \bar{\mathcal{K}}_T$:
 - $D(k)$ its type
 - k – its parent particle
 \implies Particle k lives between T_{k-} and T_k

Using Malliavin automatic differentiation

- Malliavin automatic differentiation :

$$\mathcal{W}_k := \mathbb{1}_{\{D(k)=0\}} + \mathbb{1}_{\{D(k)\neq 0\}} b_{D(k)}(T_{k-}, X_{T_{k-}}^k) \cdot \frac{\Delta W_{T_k}}{\Delta T_k}$$

The limiting random variable is :

$$\begin{aligned} \psi &:= \prod_{k \in \mathcal{K}_T} \bar{\rho}(\Delta T_k)^{-1} [g(X_T^k) - \mathbb{1}_{\{D_k \neq 0\}} g(X_{T_{k-}}^k)] \mathcal{W}_k \\ &\times \prod_{k' \in \bar{\mathcal{K}}_T \setminus \mathcal{K}_T} [\rho(\Delta T_{k'})]^{-1} b_{I_{k'}}(T_{k'}, X_{T_{k'}}^{k'}) \mathcal{W}_{k'} \end{aligned}$$

The main representation result

For independent BM W , $\tau \sim \rho$, and $T_1 := \tau \wedge T$, define :

$$A_p := \max_{\ell} \frac{|g|_{\infty}^p \vee \|W_{T_1}\|^p \|b_{\ell} \cdot \frac{W_{T_1}}{T_1}\|^p}{\bar{\rho}(T)^{p-1}}$$

$$B_p := \max_{\ell} \|\Delta_{\tau}\|^{p/2} \|b_{\ell} \cdot \frac{W_{T_1}}{T_1}\|^p \left[|b_{\ell}|_{\infty} \sup_{t \leq T} \frac{t^{-\frac{p}{2(p-1)}}}{\rho(t)} \right]^{p-1}$$

Theorem (Henry-Labordère, Oudjane, Tan, NT, Warin '16)

Assume that g Lipschitz and, for some $p > 1$,

$$\int_{A_p}^{\infty} [B_p \sum |b_{\ell}|_{\infty} |x|^{|\ell|}]^{-1} dx > T$$

Then $v(0, x) = \mathbb{E}_{0,x}[\psi]$, and $\psi \in \mathbb{L}^p$

A numerical example of dimension $d = 20$

$u(t, x) = \cos(x_1 + \dots + x_d) \exp(\alpha(T - t))$ is solution of semilinear PDE

$$\partial_t u + \frac{1}{2} \Delta u + c u (b_1 \cdot Du) + b_0 = 0.$$

- Let $\alpha = 0.2$, $c = 0.15$, $b_1 = (1 + \frac{1}{d}, 1 + \frac{2}{d}, \dots, 2)$.

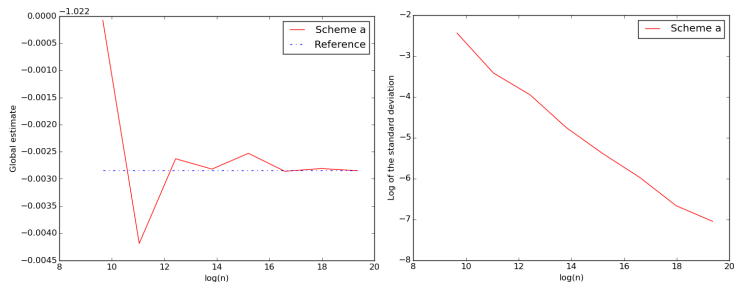


Figure – Estimation and standard deviation observed in dimension $d = 20$ depending on the log of the number of simulation used.

Monte Carlo approximation of nonlinear PDEs

Fully nonlinear PDEs... (e.g. HJB equations)

If $T_1 < T$: particle dies out, and is replaced with probability p_ℓ by

- i_ℓ particles of type 0
- j_ℓ particles of type 1 \implies first order differentiation weight
- h_ℓ particles of type 2 \implies second order differentiation weight

Automatic differentiation for particles k of type $D(k) = 2$:

$$\frac{\Delta W_T^2 - \Delta T}{(\Delta T)^2} \quad !!$$

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Linear initial value problems with constant coefficients

Let $D^\alpha := \frac{\partial^{|\alpha|}}{\partial x_1^{\alpha_1} \dots \partial x_d^{\alpha_d}}$, and consider the general PDE :

$$\sum_{n=1}^N a_n \partial_t^n u - \sum_{\alpha \in \mathbb{N}_M^d} b_\alpha \cdot D^\alpha u = F \text{ on } \mathbb{R}_+ \times \mathbb{R}^d,$$
$$\partial_t^{n-1} u(0, \cdot) = p_n f_n \text{ on } \mathbb{R}^d, \quad n = 1, \dots, N$$

where $p_n > 0$, $\sum_{n=1}^N p_n = 1$,

$f_n : \mathbb{R}^d \rightarrow \mathbb{R}$, $n \leq N$ and $F : \mathbb{R}_+ \times \mathbb{R}^d \rightarrow \mathbb{R}$, bounded continuous

Examples : Heat equation ++

- Wave equation : $\partial_t^2 u - \Delta u = F$
- Airy equation : $\partial_t u - \sum_{|\alpha|=3} b_\alpha D^\alpha u = F \dots$ to KdV equation
- Dynamic Beam equation $\partial_t^2 u - \sum_{|\alpha|=4} b_\alpha D^\alpha u = F$
- Schrödinger equation : $i\partial_t u + \Delta u = F \dots$
focalizing/defocalizing

Duhamel's Representation

For all $t \geq 0$, and $x \in \mathbb{R}^d$, we have

$$u(t, x) = \sum_{n=1}^N \int p_n f_n(y) g_n(t, x-y) dy + \int_0^t \int F(t-s, y) g_N(t-s, x-y) dy ds$$

$$g_n(t, \cdot) := \mathfrak{F}^{-1} \hat{g}_n(t, \cdot)$$

$$\hat{g}_n(t, \cdot) := \{e^{tB(\xi)^T}\}_{1, \cdot}$$

$$b(\xi) := \sum_{\alpha \in \mathbb{N}_M^d} i^{|\alpha|} b_\alpha \xi^\alpha,$$

$$B(\xi) := \left(\begin{array}{c|ccc} 0 & & & \\ \vdots & & & \\ 0 & & & \\ \hline b(\xi) & -a_1 & \cdots & -a_{N-1} \end{array} \right)$$

Examples

Airy equation : $g_1(t, z) = (3t)^{\frac{-d}{3}} \text{Ai}_b\left(\frac{z}{(3t)^{1/3}}\right)$ in terms of Airy function $\text{Ai}_b(x) := \pi^{-d} \int_{\mathbb{R}_+^d} \cos\left(\frac{-b(\xi)}{3} + x \cdot \xi\right) d\xi$. Here $\int g_1(t, \cdot) = \infty!$

Wave equation : $g_1(t, z) = \partial_t g_2(t, z)$, and

$$g_2(t, z) dz = \begin{cases} \frac{1}{2r} 1_{\{|z| < t\}} dz & \text{for } d = 1 \\ \frac{1}{2\pi\sqrt{t^2 - |z|^2}} 1_{\{|z| < t\}} dz & \text{for } d = 2 \\ \frac{\sigma_t(dz)}{4\pi t} & \text{for } d = 3 \end{cases}$$

$\sigma_t(dz)$: surface area on $\partial B(0, r)$

Beam equation ($u_{tt} + \partial_x^4 u = 0$)

$$g_1(r, z) = \partial_r g_2(r, z) \quad \text{and} \quad g_2(r, z) = r^{\frac{1}{2}} G\left(r^{-\frac{1}{2}} z\right),$$

where $G(x) = \frac{1}{\sqrt{2\pi}} + \frac{1}{2} \int_0^x \left[F_s\left(\frac{z}{\sqrt{2\pi}}\right) - F_c\left(\frac{z}{\sqrt{2\pi}}\right) \right] dz$ with the Fresnel integrals $F_c(x) := \int_0^x \cos(\pi t^2/2) dt$, $F_s(x) := \int_0^x \sin(\pi t^2/2) dt$

Probabilistic representation

Assume $G_n(t) := \int |g_n(t, y)| dy < \infty$ for all $t \geq 0$, $1 \leq j \leq n$

Set $\gamma_n(t, y) := \text{sg}\{g_n(t, y)\} G_n(t)$, $n = 1, \dots, N$, then :

$$u(t, x) = \mathbb{E} \left[\mathbb{I}_{\{\tau \geq t\}} \frac{\gamma_l(t, Z_t^l)}{\bar{\rho}(t)} f_l(X_\tau^l) + \mathbb{I}_{\{\tau < t\}} \frac{\gamma_N(\tau, Z_\tau^N)}{\rho(\tau)} F(t - \tau, X_\tau^N) \right]$$

$l, \tau, X_t^n := x - Z_t^n$, $1 \leq n \leq N$ independent with

$$\mathbb{P}[l = n] = p_n, \quad n = 1, \dots, N$$

$$\mathbb{P}[\tau \in dt] = \rho(t) \mathbb{I}_{\{t \geq 0\}} dt, \quad \rho > 0$$

$$\mathbb{P}[Z_t^n \in dz] = \frac{|g_n(t, z)|}{G_n(t)} dz$$

Representation of semilinear initial value problems

Theorem (Henry-Labordère & NT)

Under some conditions, we have

$$\xi_{t,x} := \prod_{k \in \mathcal{K}_t} \frac{\gamma_{I_k^t}(\Delta T_k^t, Z_{T_k^t}^k)}{\bar{\rho}(\Delta T_k^t)} f_{I_k^t}(X_t^k) \\
 \times \prod_{k \in \bar{\mathcal{K}}_t \setminus \mathcal{K}_t} \frac{\gamma_N(\Delta T_k^t, Z_{T_k^t}^k)}{\rho(\Delta T_k^t)} c_{J_k}(t - T_k^t, X_{T_k^t}^k) \in \mathbb{L}^1$$

and $u(t, x) := \mathbb{E}[\xi_{t,x}]$ is the unique solution of the semilinear IVP

$$\sum_{n=1}^N a_n \partial_t^n u - \sum_{\alpha \in \mathbb{N}_M^d} b_\alpha D^\alpha u = \sum_{j \geq 1} q_j c_j u^j \text{ on } \mathbb{R}_+ \times \mathbb{R}^d \\
 \partial_t^{n-1} u(0, \cdot) = f_n \text{ on } \mathbb{R}^d, \quad n = 1, \dots, N$$

Compare to Bachtin & Mueller 2010 (semilinear wave equation)

Automatic differentiation

Define the likelihood ratio (in distribution sense)

$$w_n(t, z) := \frac{Dg_n}{g_n}(t, z), \quad (t, z) \in \mathbb{R}_+ \times \mathbb{R}^d$$

and set for all $k \in \overline{\mathcal{K}}_t$

$$\mathcal{W}_k := \mathbb{1}_{\{\theta_k^t=0\}} + \mathbb{1}_{\{\theta_k^t \neq 0\}} \vec{b}_{\theta_k^t}(t - T_{k-}^t, X_{T_{k-}^t}^{k-}) \cdot w_{I_k^t}(\Delta T_k^t, Z_{T_k^t}^k)$$

where θ_k^t is the type of particle k

More general semilinear initial value problems

Theorem (Henry-Labordère & NT)

Under some conditions, we have

$$\hat{\xi}_{t,x} := \prod_{k \in \mathcal{K}_t} \mathcal{W}_k \frac{\gamma_{I_k^t}(\Delta T_k^t, Z_{T_k^t}^k)}{\bar{\rho}(\Delta T_k^t)} [f_{I_k^t}(X_t^k) - \mathbb{1}_{\{\theta_k^t \neq 0\}} f_{I_k^t}(X_{T_{k-}^k}^k)] \\ \times \prod_{k \in \bar{\mathcal{K}}_t \setminus \mathcal{K}_t} \mathcal{W}_k \frac{\gamma_N(\Delta T_k^t, Z_{T_k^t}^k)}{\rho(\Delta T_k^t)} c_{J_k}(t - T_k^t, X_{T_k^t}^k)$$

and $u(t, x) := \mathbb{E}[\hat{\xi}_{t,x}]$ is the unique solution of the semilinear IVP

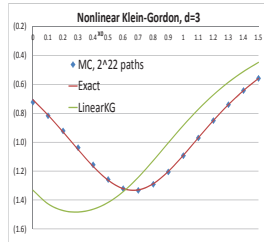
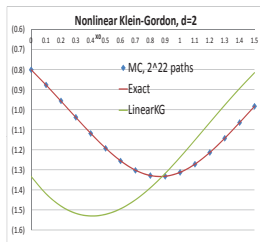
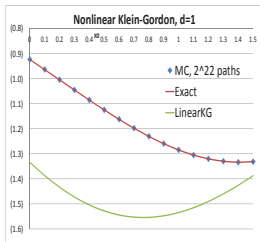
$$\sum_{n=1}^N a_n \partial_t^n u - \sum_{\alpha \in \mathbb{N}_M^d} b_\alpha D^\alpha u + \sum_{j \geq 0} q_j c_j u^{\ell_{j,0}} \prod_{h=1}^H (b_h \cdot Du)^{\ell_{j,h}} = 0 \\ \partial_t^{n-1} u(0, \cdot) = p_n f_n \text{ on } \mathbb{R}^d, \quad n = 1, \dots, N$$

Example : nonlinear wave equation 1

Klein-Gordon equation in $d = 1, \dots, 3$:

$$(\partial_{tt} - \Delta)u + u^3 + u^2 = 0, \quad u(0, x) = f_1(x), \quad \partial_t u(0, x) = f_2(x)$$

with $f_1(x) := \frac{-12}{9+2(\sum_{i=1}^d x_i)^2}$, and $f_2(x) := -\sqrt{d+1} \frac{48(\sum_{i=1}^d x_i)}{(2(\sum_{i=1}^d x_i)^2+9)^2} \implies$
 explicit solution : $u(t, x) = \frac{-12}{9+2(\sqrt{d+1}t - \sum_{i=1}^d x_i)^2}$

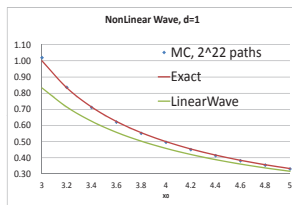


Example : nonlinear wave equation 2

Simplified Yang-Mills equation

$$\partial_{tt}u - \Delta u + u^3 + \sum_i^d u \partial_{x_i} u = 0, \quad u(0, x) = f_1(x), \quad \partial_t u(0, x) = f_2(x)$$

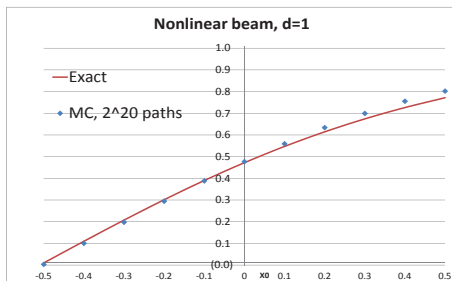
with $f_1(x) = -\frac{d}{d - \sum_{i=1}^d x_i}$, $f_2(x) = \sqrt{d} \frac{d}{(d - \sum_{i=1}^d x_i)^2}$
 \implies explicit solution : $u(t, x) = -\frac{d}{d + \sqrt{d}t - \sum_{i=1}^d x_i}$



Example : nonlinear Beam equation in 1d

$$\partial_t^2 u + \partial_x^3 u + u^2 + h(t, x) = 0, \quad u(0, x) = \tanh(x), \quad \partial_t u(0, x) = \cosh(x)^{-2}$$

\implies explicit solution is $u(t, x) = \tanh(x + t)$ (for suitable choice of h)

Figure – Numerical solution of nonlinear beam PDE $t = 0.5$.

Example : Gross-Pitaevskii PDE

For a constant $h(= -1$ in our numerics), consider

$$i\partial_t u(t, x) = -\frac{1}{2}\Delta u(t, x) + h|u(t, x)|^2 u(t, x), \quad x \in \mathbb{R}^d$$

$$u(0, x) = f_1(x) := \sqrt{d} [\cosh(\sum_{i=1}^d x_i)]^{-1}$$

\implies Explicit solution $u(t, x) = e^{\frac{idt}{2}} \sqrt{d} [\cosh(\sum_{i=1}^d x_i)]^{-1}$

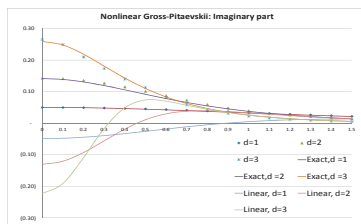
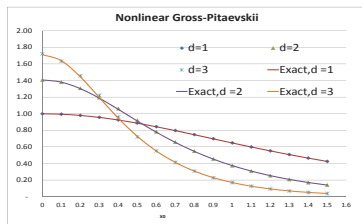


Figure – $Re(u(t, x_0))$ (left) and $Im(u(t, x_0))$ (right) for $d = 1, 2, 3$, $t = 0.1$

Concluding remarks

- Bounded space domain (including elliptic PDEs) : serious difficulties for gradient nonlinearity, Agarwal & Claisse '17
- Variable coefficients :
 - parabolic equations
 - more general Cauchy problems...
- Exploding representation for wellposed equation !
 - backward iteration over “short time steps,” Bouchard, Tan & Zhou '17
 - Beyond power nonlinearity